# Smoothed particle hydrodynamics for fluid dynamics

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2 / 50

• If you need a multi-core machine: apply for a CCV account https://www.ccv.brown.edu/

Outline	Outline
<ol> <li>Background         <ul> <li>hydrodynamic equations</li> <li>numerical methods</li> </ul> </li> <li>Mathematics of smoothed particle hydrodynamics         <ul> <li>some facts and basic mathematics</li> <li>kernel and particle approximations of a function</li> <li>first and second derivatives</li> </ul> </li> <li>Particles for hydrodynamics         <ul> <li>continuity and pressure force</li> <li>viscous force</li> </ul> </li> </ol>	<ol> <li>Background         <ul> <li>hydrodynamic equations</li> <li>numerical methods</li> </ul> </li> <li>Mathematics of smoothed particle hydrodynamics         <ul> <li>some facts and basic mathematics</li> <li>kernel and particle approximations of a function</li> <li>first and second derivatives</li> </ul> </li> <li>Particles for hydrodynamics         <ul> <li>continuity and pressure force</li> <li>viscous force</li> </ul> </li> </ol>
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1/50

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#### Background

- hydrodynamic equations
- numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- 3) Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- 4 Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
- equations of motion
- 5 Numerical errors
- 6 Research challenges
- 7 A short excursion to other particle methods

# Conservation law of momentum: Euler equations

Total pressure force acting on the volume (surface to volume integral)

$$-\oint pd\mathbf{f} = -\int \nabla pdV. \tag{5}$$

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For a unit of volume, momentum equations in Lagrangian form read

$$\rho \frac{d\mathbf{v}}{dt} = -\nabla p \quad \text{or} \quad \frac{d\mathbf{v}}{dt} = -\frac{\nabla p}{\rho}.$$
(6)

Considering the particle derivative is related to the partial derivatives as

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla, \tag{7}$$

the Euler equations in Eulerian form read

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\frac{\nabla p}{\rho}.$$
(8)

# Conservation law of mass: continuity equation

Total mass flows out of the volume V (per unit time) by surface integral

 $\oint \rho \mathbf{v} \cdot d\mathbf{f},\tag{1}$ 

where  $\rho$  density,  ${\bf v}$  velocity and  $d{\bf f}$  is along the outward normal. The decrease of the mass in the volume (per unit time)

$$\frac{\partial}{\partial t} \int \rho dV. \tag{2}$$

For a mass conservation, we have an equality

$$-\frac{\partial}{\partial t}\int \rho dV = \oint \rho \mathbf{v} \cdot d\mathbf{f} = \int \nabla \cdot (\rho \mathbf{v}) dV, \qquad (3)$$

which is valid for an arbitrary V. The continuity equation reads

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0. \tag{4}$$

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# Conservation law of momentum: Navier-Stokes equations

For real fluids, we need to add in viscous stress due to irreversible process and assume that the viscous stress depends only *linearly* on derivatives of velocity.

Without derivation, the Navier-Stokes equations read

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\frac{1}{\rho} \left[ \nabla \rho + \eta \bigtriangleup \mathbf{v} + (\zeta + \eta/3) \nabla \nabla \cdot \mathbf{v} \right]$$
(9)

For an incompressible fluid  $\rho = const.$  and  $\nabla \cdot \mathbf{v} = 0$ . Therefore, the momentum equations simplify to

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\frac{1}{\rho} \left( \nabla \rho + \eta \bigtriangleup \mathbf{v} \right).$$
(10)

For a compressible fluid, an equation of state is called for

$$p = p(\rho, T = T_0). \tag{11}$$

#### Background

- hydrodynamic equations
- numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
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  - first and second derivatives
- 3 Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- 4 Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
  - equations of motion
- Numerical errors

Prof. Karniadakis will cover the mesh-based methods in other lectures

- finite difference method
- spectral h/p element method

• ... ...

<ul> <li>6 Research challenges</li> <li>7 A short excursion to other particle methods</li></ul>	
Mesh-free discretizations: mesh-free = mess-free?	Outline
<ul> <li>Some particle methods <ul> <li>smoothed particle hydrodynamics (SPH)</li> <li>moving least square methods (MLS)</li> <li>vortex method</li> <li>Voronoi tesselation</li> <li></li> </ul> </li> <li>mesh-free ≈ mess-free <ul> <li>no mesh generation</li> <li>Lagrangian, no v · ∇v</li> <li>complex moving boundary</li> <li>incorporation of new physics</li> </ul> </li> </ul>	<ol> <li>Background         <ul> <li>hydrodynamic equations</li> <li>numerical methods</li> </ul> </li> <li>Mathematics of smoothed particle hydrodynamics         <ul> <li>some facts and basic mathematics</li> <li>kernel and particle approximations of a function</li> <li>first and second derivatives</li> </ul> </li> <li>Particles for hydrodynamics         <ul> <li>continuity and pressure force</li> <li>viscous force</li> </ul> </li> <li>Classical mechanics for particles ⇒ hydrodynamics         <ul> <li>density estimate</li> <li>equations of motion</li> </ul> </li> </ol>
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- **5** Numerical errors
- 6 Research challenges
- 7 A short excursion to other particle methods

# Integral representation of a function

- Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- 4 Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
- equations of motion
- 5 Numerical errors
- 6 Research challenges
- 7 A short excursion to other particle methods

# Outline

- 1 Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
  - equations of motion
- Numerical errors
- Research challenges
- A short excursion to other particle methods

• It was invented in 1970s (author?) [12, 8].

Given a scalar function f(r) of spatial coordinate r, its integral representation reads

$$f(r) = \int f(r')\delta(r-r')dr', \qquad (12)$$

where the Dirac delta function reads

$$\delta(r-r') \begin{cases} \infty, & r=r'\\ 0, & r\neq r' \end{cases}$$
(13)

and the constraint of normalization is

$$\int_{\infty}^{\infty} \delta(r) dr = 1.$$
 (14)



# SPH 1<sup>st</sup> step: smoothing or kernel approximation

(author?) [8]; (author?) [12] Replace  $\delta$  with another smoothly weighting function w:

$$f(r) \approx f_k(r) = \int f(r')w(r-r',h)dr', \qquad (15)$$

where kernel w has properties

- smoothness
- compact with h as parameter
- $im_{h\to 0} w(r-r',h) = \delta(r-r')$
- symmetric

**6** ... ...

compact: B-splines, Wendland functions ...

(author?) [15, 16, 19]

Gaussian:  $\frac{1}{a\sqrt{\pi}}e^{-r^2/a^2}$ 

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## Compact kernel and its normalization

# SPH 2<sup>nd</sup> step: summation or particle approximation

• a cubic function as reads (h = 1 for simplicity)

$$w(r) = \begin{cases} C_D(1-r)^3, & r < 1; \\ 0, & r \ge 1. \end{cases}$$
(16)

If we require the constraint of normalization in two dimension

$$\int_0^{2\pi} \int_0^1 C_2 (1-r)^3 r dr d\theta = 1 \iff C_2 = \frac{10}{\pi}$$
(17)

• a piecewise quintic function reads

$$w(r) = C_D \left\{ egin{array}{ccc} (3-s)^5 - 6(2-s)^5 + 15(1-s)^5, & 0 \leq s < 1\ (3-s)^5 - 6(2-s)^5, & 1 \leq s < 2\ (3-s)^5, & 2 \leq s < 3\ 0, & s \geq 3, \end{array} 
ight.$$

where s = 3r/h and  $C_2 = 7/(478\pi h^2)$  and  $C_3 = 1/(120\pi h^3)$ . •  $f(r) = f_k(r) + error(h)$ 

#### An example: evaluation of density and arbitrary function

 $\forall i \text{ of particle index, mass } m_i, \text{ density } \rho_i, \text{ and } V_i = m_i / \rho_i.$ 

$$f_{s}(r) = \sum_{i}^{N_{neigh}} f_{i}w(r - r_{i}, h)V_{i} = \sum_{i}^{N_{neigh}} \frac{m_{i}}{\rho_{i}}f_{i}w(r - r_{i}, h).$$
(22)

• What is the density at an arbitrary position r?

$$\rho_s(r) = \sum_{i}^{N_{neigh}} \frac{m_i}{\rho_i} \rho_i w(r - r_i, h) = \sum_{i}^{N_{neigh}} m_i w(r - r_i, h).$$
(23)

• What is the density of a particle at  $r_j$ ?

$$\rho_s(r_j) = \sum_i^{N_{neigh}} m_i w(r_j - r_i, h).$$
(24)

• What is the value of a function of a particle at  $r_j$ ?

$$f_{s}(r_{j}) = \sum_{i}^{N_{neigh}} f_{i} \frac{m_{i}}{\rho_{i}} w(r_{j} - r_{i}, h) = \sum_{i}^{N_{neigh}} f_{i} W_{ji} = f_{j}$$
(25)

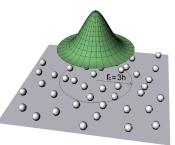
Integral  $\iff$  summation

$$f_{k}(r) = \int f(r')w(r-r',h)dr'(19)$$
  
$$f_{s}(r) = \sum_{i}^{N_{neigh}} f_{i}w(r-r_{i},h)V_{i}, (20)$$

where  $V_i$  is a distance, area and volume in 1D, 2D, and 3D, respectively. Therefore,

$$f_k(r) \approx f_s(r)$$

• 
$$f_k(r) = f_s(r) + error(\Delta r, h)$$



(21) summation within compact support

# Outline

- Background
   hydrodynamic equations
  - hydrodynamic equations
  - numerical methods

#### 2 Mathematics of smoothed particle hydrodynamics

- some facts and basic mathematics
- kernel and particle approximations of a function
- first and second derivatives
- 3 Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- 4 Classical mechanics for particles ⇒ hydrodynamics
   density estimate
  - equations of motion
- 5 Numerical errors

- 6 Research challenges
- 7 A short excursion to other particle methods

$$\nabla_r f(r) \approx \nabla_r f_k(r) = \nabla_r \int f(r') w(r - r', h) dr'$$
(27)

$$\nabla_r f_k(r) = \int \nabla_r f(r') w(r-r',h) dr' + \int f(r') \nabla_r w(r-r',h) dr' \quad (28)$$

$$\nabla_r f_k(r) = \int f(r') \nabla_r w(r - r', h) dr'$$
(29)

$$\nabla_r f(r) \approx \nabla_r f_k(r) \approx \nabla_r f_s(r) = \sum_{i}^{N_{neigh}} \frac{m_i}{\rho_i} f(r') \nabla_r w(r - r', h) \tag{30}$$

$$\nabla_r \cdot f(r) \approx \nabla_r \cdot f_k(r) \approx \nabla_r \cdot f_s(r) = \sum_{i}^{N_{neigh}} \frac{m_i}{\rho_i} f(r') \cdot \nabla_r w(r - r', h) \quad (31)$$

$$\nabla_r \times f(r) \approx \nabla_r \times f_k(r) \approx \nabla_r \times f_s(r) = \sum_{i}^{N_{neigh}} \frac{m_i}{\rho_i} f(r') \times \nabla_r w(r - r', h)$$
(32)

# Second derivatives

Note that we have following identity (author?) [4]

$$\int d\mathbf{r}' \left[ f(\mathbf{r}') - f(\mathbf{r}) \right] \frac{\partial w(|\mathbf{r}' - \mathbf{r}|)}{\partial r'} \frac{1}{r_{ij}} \mathbf{e}_{ij} \left[ 5 \frac{(\mathbf{r}' - \mathbf{r})^{\alpha} (\mathbf{r}' - \mathbf{r})^{\beta}}{(\mathbf{r}' - \mathbf{r})^{2}} - \delta^{\alpha\beta} \right]$$
$$= \nabla^{\alpha} \nabla^{\beta} f(\mathbf{r}) + \mathcal{O}(\nabla^{4} f h^{2}).$$
(33)

Therefore,

$$\frac{1}{\rho_i} \left( \nabla^2 \mathbf{v} \right) = -2 \sum_{j}^{N_{neigh}} \frac{m_j}{\rho_i \rho_j} \frac{\partial w_{ij}}{\partial r} \mathbf{v}_{ij}$$
(34)

$$\frac{1}{\rho_i} \left( \nabla \nabla \cdot \mathbf{v} \right) = -\sum_{j}^{N_{neigh}} \frac{m_j}{\rho_i \rho_j} \frac{\partial w_{ij}}{\partial r} \left( 5 \mathbf{e}_{ij} \cdot \mathbf{v}_{ij} \mathbf{e}_{ij} - \mathbf{v}_{ij} \right)$$
(35)

#### Outline

- Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a functionfirst and second derivatives

#### Operation of the second sec

- continuity and pressure force
- viscous force
- ④ Classical mechanics for particles ⇒ hydrodynamics
   density estimate
  - equations of motion
- 5 Numerical errors
- 6 Research challenges
- A short excursion to other particle methods

(36)

1 Background

hydrodynamic equationsnumerical methods

• first and second derivatives

• continuity and pressure force

3 Particles for hydrodynamics

• viscous force

• density estimate

Numerical errors

• equations of motion

• some facts and basic mathematics

Mathematics of smoothed particle hydrodynamics

• kernel and particle approximations of a function

# Particles for hydrodynamics

• continuity equation is accounted for by

$$\rho_i = \sum_j^{N_{neigh}} m_j W_{ij}, \quad \dot{\mathbf{r}}_i = \mathbf{v}_i$$
(37)

 $\bullet$  pressure force:  $-\nabla \mathbf{p}/\rho$ 

$$\mathbf{F}_{i}^{C} = \sum_{j}^{N_{neigh}} \mathbf{F}_{ij}^{C} = \sum_{j}^{N_{neigh}} - m_{j} \left(\frac{p_{j}}{\rho_{j}^{2}}\right) \frac{\partial w}{\partial r_{ij}} \mathbf{e}_{ij},$$
(38)

• bad: not antisymmetric by swapping *i* and *j* 

• recognize 
$$-\nabla p/\rho = -\frac{p}{\rho^2}\nabla \rho - \nabla \frac{p}{\rho}$$

$$\mathbf{F}_{ij}^{C} = -m_j \left(\frac{p_i}{\rho_i^2} + \frac{p_j}{\rho_j^2}\right) \frac{\partial w}{\partial r_{ij}} \mathbf{e}_{ij}, \qquad (39)$$

26 / 50

# Outline

- Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics

A short excursion to other particle methods

- some facts and basic mathematics
- kernel and particle approximations of a function
- first and second derivatives

## 3 Particles for hydrodynamics

- continuity and pressure force
- viscous force
- igside Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
  - equations of motion
- Numerical errors
- Research challenges
- A short excursion to other particle methods

# viscous force

In general

$$\mathbf{F}_{ij}^{D} = \frac{m_{j}}{\rho_{i}\rho_{j}r_{ij}}\frac{\partial w}{\partial r_{ij}}\left[\left(\frac{5\eta}{3}-\zeta\right)\mathbf{v}_{ij}+\left(5\zeta+\frac{5\eta}{3}\right)\mathbf{e}_{ij}\cdot\mathbf{v}_{ij}\mathbf{e}_{ij}\right]$$
(40)

For inompression flows  $\nabla\cdot {\bf v}={\bf 0},$  therefore,

$$\sum_{j}^{N} \frac{5}{\rho_{i}\rho_{j}r_{ij}} \frac{\partial w_{ij}}{r_{ij}} \mathbf{e}_{ij} \cdot \mathbf{v}_{ij} \mathbf{e}_{ij} \approx \sum_{j}^{N} \frac{1}{\rho_{i}\rho_{j}r_{ij}} \frac{\partial w_{ij}}{\partial r_{ij}} \mathbf{e}_{ij}.$$
 (41)

$$\mathbf{F}_{ij}^{D} = 2\eta \frac{m_j}{\rho_i \rho_j r_{ij}} \frac{\partial w_{ij}}{\partial r_{ij}} \mathbf{v}_{ij} \approx 10\eta \frac{m_j}{\rho_i \rho_j r_{ij}} \frac{\partial w_{ij}}{\partial r_{ij}} \mathbf{e}_{ij} \cdot \mathbf{v}_{ij} \mathbf{e}_{ij}.$$
(42)

Either choice is fine, but they are different.

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• continuity equation:

$$\rho_i = \sum_{i}^{N_{neigh}} m_j W_{ij}, \quad \dot{\mathbf{r}}_i = \mathbf{v}_i$$
(43)

• momentum equations: (author?) [4, 11]

$$\dot{\mathbf{v}}_{i} = \sum_{j \neq i}^{N_{neigh}} \left( \mathbf{F}_{ij}^{C} + \mathbf{F}_{ij}^{D} \right), \tag{44}$$

$$\mathbf{F}_{ij}^{C} = -m_{j} \left( \frac{p_{i}}{\rho_{i}^{2}} + \frac{p_{j}}{\rho_{j}^{2}} \right) \frac{\partial w}{\partial r_{ij}} \mathbf{e}_{ij}, \qquad (45)$$

$$\mathbf{F}_{ij}^{D} = \frac{m_{j}}{\rho_{i}\rho_{j}r_{ij}}\frac{\partial w}{\partial r_{ij}}\left[\left(\frac{5\eta}{3}-\zeta\right)\mathbf{v}_{ij}+\left(5\zeta+\frac{5\eta}{3}\right)\mathbf{e}_{ij}\cdot\mathbf{v}_{ij}\mathbf{e}_{ij}\right] (46)$$

• weakly compressible: (author?) [2, 13]

$$p = c_T^2 \rho, \quad or \quad p = p_0 \left[ \left( \frac{\rho}{\rho_r} \right)^{\gamma} - 1 \right]$$
 (47)

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29 / 50

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31 / 50

 $p_0$  relates to an artificial sound speed  $c_{\mathcal{T}}$ 

# Outline

 Background hydrodynamic equations • numerical methods Mathematics of smoothed particle hydrodynamics • some facts and basic mathematics • kernel and particle approximations of a function • first and second derivatives • continuity and pressure force • viscous force 4 Classical mechanics for particles  $\Rightarrow$  hydrodynamics • density estimate • equations of motion 5 Numerical errors 6 Research challenges A short excursion to other particle methods ・ロト ・ 同ト ・ ヨト ・ ヨト 30 / 50

# Outline

- 1 Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- Particles for hydrodynamics
  - continuity and pressure force
  - viscous force

#### 4 Classical mechanics for particles $\Rightarrow$ hydrodynamics

- density estimate
- equations of motion
- 5 Numerical errors
- 6 Research challenges
- A short excursion to other particle methods

# Density estimate or sampling

Given a set of point particles with mass  $m_i$ , what is the density estimate for a position at r.

$$\rho_{s}(\mathbf{r}) = \sum_{i}^{N_{neigh}} m_{i} w(\mathbf{r} - \mathbf{r}_{i}, h).$$
(48)

where kernel w has properties

- smoothness
- 2 compact with h as parameter

$$\bigcirc \int w(r-r',h)dr'=1$$

- symmetric
- 5 ... ...

Eq. (48) is more fundamental than the summation form presented early

$$f_{s}(\mathbf{r}) = \sum_{i}^{N_{neigh}} f_{i} \frac{m_{i}}{\rho_{i}} w(\mathbf{r} - \mathbf{r}_{i}, h).$$
(49)

# Background hydrodynamic equations numerical methods Mathematics of smoothed particle hydrodynamics some facts and basic mathematics kernel and particle approximations of a function first and second derivatives

- Particles for hydrodynamics
  - continuity and pressure force
  - viscous force

#### 4 Classical mechanics for particles $\Rightarrow$ hydrodynamics

- density estimate
- equations of motion
- 5 Numerical errors
- 6 Research challenges
- 7 A short excursion to other particle methods

# Euler-Lagrangian equations

$$\delta S = \int \left( \frac{\partial L}{\partial \mathbf{v}} \cdot \delta \mathbf{v} + \frac{\partial L}{\partial \mathbf{r}} \cdot \delta \mathbf{r} \right) = 0$$
(54)

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consider  $\delta \mathbf{v} = d(\delta \mathbf{r})/dt$  and  $d/dt = \partial/\partial t + \mathbf{v} \cdot \nabla$ 

#### ₩

$$\delta S = \int \left\{ \left[ -\frac{d}{dt} \left( \frac{\partial L}{\partial \mathbf{v}} \right) + \frac{\partial L}{\partial \mathbf{r}} \right] \cdot \delta \mathbf{r} \right\} dt + \left[ \frac{\partial L}{\partial \mathbf{v}} \cdot \delta \mathbf{r} \right]_{t_0}^t = 0 \quad (55)$$

assume variation vanishes at start and end times and furthermore,  $\delta \mathbf{r}$  is arbitrary. Therefore, we have the Euler-Lagrangian equations

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \mathbf{v}_i}\right) - \frac{\partial L}{\partial \mathbf{r}_i} = 0.$$
(56)

# Least action

Define the Lagrangian L as

$$L = T - U, \tag{50}$$

where T and U are kinetic and potential energies, respectively. For a set of particles

$$L = \sum_{i}^{N} m_i \left( \frac{1}{2} v_i^2 + u_i(\rho_i, s) \right)$$
(51)

Define the action as

$$S = \int L dt.$$
 (52)

Minimizing S such that  $\delta S = \int \delta L dt = 0$ , where  $\delta$  is a variation with respect to particle coordinate  $\delta \mathbf{r}$ . We have **(author?)** [17]

$$\delta S = \int \left( \frac{\partial L}{\partial \mathbf{v}} \cdot \delta \mathbf{v} + \frac{\partial L}{\partial \mathbf{r}} \cdot \delta \mathbf{r} \right) = 0$$
 (53)

# Equation of motions for particles

From the Lagrangian  $L = \sum_{i}^{N} m_i \left(\frac{1}{2}v_i^2 + u_i\right)$  we know

$$\frac{\partial L}{\partial \mathbf{v}_i} = m_i \mathbf{v}_i, \quad \frac{\partial L}{\partial \mathbf{r}_i} = -\sum_j^{N_{neigh}} m_j \frac{\partial u_j}{\partial \rho_j} \frac{\partial \rho_j}{\partial \mathbf{r}_j}$$
(57)

Some basic thermodynamics: dU = TdS - PdVSince  $V = m/\rho$ , so  $dV = -md\rho/\rho^2$ . For per unit mass we have

$$du = Tds - \frac{P}{\rho^2}d\rho.$$
(58)

For a reversible process ds = 0, therefore  $\partial u_i / \partial \rho_i = p / \rho^2$ . Put everything known into the Euler-Lagrangian equations, we get

$$\dot{\mathbf{v}}_{i} = \sum_{j \neq i}^{N_{neigh}} - m_{j} \left( \frac{p_{i}}{\rho_{i}^{2}} + \frac{p_{j}}{\rho_{j}^{2}} \right) \frac{\partial w}{\partial r_{ij}} \mathbf{e}_{ij}.$$
(59)

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## Conservation laws

Euler hydrodynamics

- total mass  $M = \sum_{i}^{N} m_{i}$ .
- total linear momentum

$$\frac{d}{dt}\sum_{i}^{N}m_{i}\mathbf{v}_{i}=\sum_{i}^{N}m_{i}\frac{d\mathbf{v}_{i}}{dt}=\sum_{i}^{N}\sum_{j}^{N}-m_{i}m_{j}\left(\frac{p_{i}}{\rho_{i}^{2}}+\frac{p_{j}}{\rho_{j}^{2}}\right)\frac{\partial w}{\partial r_{ij}}\mathbf{e}_{ij}=0.$$
(60)

• total angular momentum

$$\frac{d}{dt}\sum_{i}^{N}\mathbf{r}_{i}\times m_{i}\mathbf{v}_{i}=\sum_{i}^{N}m_{i}\left(\mathbf{r}_{i}\times\frac{d\mathbf{v}_{i}}{dt}\right)$$
(61)

$$= \sum_{i}^{N} \sum_{j}^{N} -m_{i}m_{j} \left(\frac{p_{i}}{\rho_{i}^{2}} + \frac{p_{j}}{\rho_{j}^{2}}\right) \frac{\partial w}{\partial r_{ij}} (\mathbf{r}_{i} \times \mathbf{e}_{ij}) = 0.$$
 (62)

Similarly for the viscous forces.

# Errors in density estimate: kernel error

Recall the kernel approximation

$$\rho_k(\mathbf{r}) = \int \rho(\mathbf{r}') w(\mathbf{r} - \mathbf{r}', h) d\mathbf{r}', \qquad (63)$$

Expanding  $\rho(r')$  by Taylor series around **r** 

$$\rho_{k}(\mathbf{r}) = \rho(\mathbf{r}) \int w(\mathbf{r} - \mathbf{r}', h) d\mathbf{r}' + \nabla \rho(\mathbf{r}) \cdot \int (\mathbf{r}' - \mathbf{r}) w(\mathbf{r} - \mathbf{r}', h) d\mathbf{r}' + \nabla^{\alpha} \nabla^{\beta} \rho(\mathbf{r}) \int \delta \mathbf{r}'^{\alpha} \delta \mathbf{r}^{\beta} w(\mathbf{r} - \mathbf{r}', h) d\mathbf{r}' + O(h^{3}).$$
(64)

Recall  $\int w(\mathbf{r} - \mathbf{r}', h) d\mathbf{r}' = 1$  and odd terms vanish due to symmetric w,

$$\rho(\mathbf{r}) = \rho_k(\mathbf{r}) + O(h^2). \tag{65}$$

# Outline

		<ul> <li>Background</li> <li>hydrodynamic equations</li> </ul>
$m_j \left( rac{p_i}{ ho_i^2} + rac{p_j}{ ho_j^2}  ight) rac{\partial w}{\partial r_{ij}} \mathbf{e}_{ij}$	<sub>j</sub> = 0.	<ul> <li>numerical methods</li> <li>Mathematics of smoothed particle hydrodynamics</li> <li>some facts and basic mathematics</li> <li>kernel and particle approximations of a function</li> <li>first and second derivatives</li> </ul>
	(60)	<ul> <li>Particles for hydrodynamics</li> <li>continuity and pressure force</li> <li>viscous force</li> </ul>
$\left(\mathbf{r}_{i}\times\frac{d\mathbf{v}_{i}}{dt}\right)$	(61)	<ul> <li>④ Classical mechanics for particles ⇒ hydrodynamics</li> <li>● density estimate</li> </ul>
$\frac{\partial w}{\partial r_{ij}}\left(\mathbf{r}_{i}\times\mathbf{e}_{ij}\right)=0.$	(62)	<ul> <li>equations of motion</li> <li>Numerical errors</li> <li>Research challenges</li> </ul>
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# Errors for a function f: kernel error and summation error

Similarly as for density estimate:

$$f(\mathbf{r}) = f_k(\mathbf{r}) + O(h^2). \tag{66}$$

$$f_k(\mathbf{r}_i) \approx f_s(\mathbf{r}_i) = \sum_j^{N_{neigh}} \frac{m_j}{\rho_j} f_j w(\mathbf{r}_i - \mathbf{r}_j, h).$$
(67)

Let us do Taylor series on 
$$f(\mathbf{r}_j)$$
 around  $\mathbf{r}_i$   
 $f_s(\mathbf{r}_i) = f_i \sum_j^{N_{neigh}} \frac{m_j}{\rho_j} w(\mathbf{r}_{ij}, h) + \nabla f_i \cdot \sum_j^{N_{neigh}} \mathbf{r}_{ji} \frac{m_j}{\rho_j} w(\mathbf{r}_{ij}, h) + O(h^2).$  (68)

To have error of  $O(h^2)$ , we need

$$\sum_{j}^{N} \frac{m_{j}}{\rho_{i}} w(\mathbf{r}_{ij}) = 1, \quad \sum_{j}^{N} \mathbf{r}_{ji} \frac{m_{j}}{\rho_{i}} w(\mathbf{r}_{ij}) = 0, \tag{69}$$

## Challenges

- 1 Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- Particles for hydrodynamics
  - continuity and pressure force
  - viscous force
- 4) Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
- equations of motion
- 5 Numerical errors

#### 6 Research challenges

7 A short excursion to other particle methods

- error analysis due to particle configurations
- consistency and conservation at the same time
- convergence for a practical purpose
- coarse-graining from molecular dynamics

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# Outline

- Background
  - hydrodynamic equations
  - numerical methods
- 2 Mathematics of smoothed particle hydrodynamics
  - some facts and basic mathematics
  - kernel and particle approximations of a function
  - first and second derivatives
- Particles for hydrodynamics
  - continuity and pressure force
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- 4 Classical mechanics for particles  $\Rightarrow$  hydrodynamics
  - density estimate
  - equations of motion
- 5 Numerical errors
- Research challenges
- A short excursion to other particle methods

# Algorithmic similarity: pairwise forces within short range $r_c$

• in a nutshell,  $\forall$  particle *i* in **SPH**, **SDPD**, **DPD**, or **MD**, the EoM:

$$\dot{\mathbf{v}}_{i} = \sum_{j \neq i} \left( \mathbf{F}_{ij}^{C} + \mathbf{F}_{ij}^{D} + \mathbf{F}_{ij}^{R} \right)$$
(70)

- options for different components
  - weighting kernel or potential gradient in MD
  - equation of state
  - density field
  - thermal fluctuations
  - canonical ensemble / NVT: thermostat
  - ... ...

```
SPH: (author?) [14]
```

SDPD: (author?) [4]

DPD: (author?) [10]; (author?) [5]; (author?) [9]

 $\mathsf{MD:} \ \textbf{(author?)} \ [1]; \ \textbf{(author?)} \ [7]; \ \textbf{(author?)} \ [6]; \ \textbf{(author?)} \ [18]$ 

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•  $\sim$  12,000 SDPD particles (author?) [3]

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