## LECTURE 2: VECTORS AND DOT PRODUCTS

Welcome to the magical world of vectors, which are useful companions in our multivariable adventure. This topic calls for an obligatory Skyrim joke: "Today I learned about vectors, but then I took an *arrow* to the knee"

#### 1. **DEFINITION**

A vector is an arrow with 2 (or 3) components

Example 1:

**Definition:** 

Draw  $\mathbf{a} = \langle 2, 3 \rangle$ 

All you need to do is draw an arrow that goes 2 units to the right and 3 units up:



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This time you go 2 units to the left and 1 unit down

Warning: Do not confuse the vector  $\langle -2, -1 \rangle$  with the point (-2, -1). Unlike points, vectors have a sense of direction (here right/left and up/down).



Of course, you can do the same thing in 3 dimensions



Here you go 2 units to the front, 2 units to the left, and then 5 units up.



You can even find vectors connecting two points



Draw the vector **a** from (1,2) to (3,4)

$$\mathbf{a} = \langle 3 - 1, 4 - 2 \rangle = \langle 2, 2 \rangle$$



Note: The order matters here; do not confuse this with  $\langle 1 - 3, 2 - 4 \rangle = \langle -2, -2 \rangle$ , which goes the other way around

#### 2. Applications

The world of vectors is filled with applications:

(1) A velocity vector represents the direction and magnitude in which a person or an object is moving



Here the person is walking northeast with a speed of 2 mph both to the right and up.

(2) The **force** that an object exerts on another can be represented by a **force** vector; think gravity for example

For example, in engineering, if the force acting on a bridge is too big, it might collapse!



- (3) Also appears in electricity and magnetism
- (4) Even appears in economics, describes the "trend" of a certain company. For instance, if a company sells Apples and Bananas, the graph below shows that the current trend is for the company to produce more Bananas than Apples



## 3. BASIC OPERATIONS

Given two vectors, what can we do to them? Just like for points, we can add them:

Example 5: (Addition)  
If 
$$\mathbf{a} = \langle 1, 2 \rangle$$
 and  $\mathbf{b} = \langle 3, 4 \rangle$ , then  
 $\mathbf{a} + \mathbf{b} = \langle 1 + 3, 2 + 4 \rangle = \langle 4, 6 \rangle$ 

You can represent this as gluing the two vectors together (not drawn to scale)



You can also multiply a vector by a number





Notice all those vectors lie on the same line, but  $-\mathbf{a}$  and  $-2\mathbf{a}$  go in the opposite direction.

Note: Facts like  $\mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$  are still true for vectors.

You can also subtract two vectors, which has a nice geometric interpretation





**Interpretation:** If you compare the picture with the one with  $\mathbf{a} + \mathbf{b}$ , notice that  $\mathbf{a} + \mathbf{b}$  and  $\mathbf{a} - \mathbf{b}$  are the diagonals of the parallelogram formed by  $\mathbf{a}$  and  $\mathbf{b}$ .



Example 8: (Parallel Vectors)	
Consider $\mathbf{a} = \langle 1, 2 \rangle$ and $\mathbf{b} = \langle 3, 6 \rangle$	

Notice  $\mathbf{b} = 3\mathbf{a}$ . Also, geometrically,  $\mathbf{a}$  and  $\mathbf{b}$  are parallel, as in the following figure



**Definition:** (Parallel Vectors)

**a** and **b** are **parallel** if  $\mathbf{b} = c \mathbf{a}$  for some real number c (or  $\mathbf{a} = c \mathbf{b}$  for some c)

In other words, one vector is a multiple of the other one.

# Example 9: Are the following vectors parallel? (a) $\langle 2, 4 \rangle$ and $\langle -4, -8 \rangle$ (b) $\langle 3, 5 \rangle$ and $\langle 2, 9 \rangle$ (c) $\langle 1, 5, 2 \rangle$ and $\langle 3, 15, 6 \rangle$

#### Answers:

- (a) Yes,  $\langle -4, -8 \rangle = (-2) \langle 2, 4 \rangle$  (negative numbers are ok)
- (b) No,  $\langle 2, 9 \rangle$  is not a multiple of  $\langle 3, 5 \rangle$
- (c) Yes,  $\langle 3, 15, 6 \rangle = 3 \langle 1, 5, 2 \rangle$

#### 4. Lengths

Another special operation you can do to a vector is to take its length **Example 10:** 

Find the length  $\|\mathbf{a}\|$  of  $\mathbf{a} = \langle 1, 2 \rangle$ 

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Think Pythagorean theorem, it's the length of the hypotenuse of a triangle with sides 1 and 2



Note: The book uses  $|\mathbf{a}|$  instead of  $||\mathbf{a}||$ , but this can be easily confused with |x| (absolute value).

## Example 11:

Find  $\|\mathbf{b}\|$ , where  $\mathbf{b} = \langle -3, 4 \rangle$ 

$$\|\mathbf{b}\| = \sqrt{(-3)^2 + 4^2} = \sqrt{9 + 16} = \sqrt{25} = 5$$

This also works in higher dimensions

## Example 12:

Find  $\|\mathbf{a}\|$ , where  $\mathbf{a} = \langle 1, 2, 4 \rangle$ 

$$\|\mathbf{a}\| = \sqrt{1^2 + 2^2 + 4^2} = \sqrt{1 + 4 + 16} = \sqrt{21}$$

It is sometimes useful to produce vectors of length 1 (called unit vectors). Luckily, this is easy to do:



$$\|\mathbf{a}\| = \sqrt{1^2 + 2^2} = \sqrt{5}$$

$$\frac{\mathbf{a}}{\|\mathbf{a}\|} = \frac{1}{\sqrt{5}} \left\langle 1, 2 \right\rangle = \left\langle \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right\rangle$$

What makes this special is that the new "normalized" vector has the **same** direction as the original one, but now it has length 1 (think same direction, but smaller magnitude)



Example 14:

Normalize  $\mathbf{b} = \langle 2, 0, 3 \rangle$ 

$$\|\mathbf{b}\| = \sqrt{2^2 + 0 + 3^2} = \sqrt{4 + 9} = \sqrt{13}$$

$$\frac{\mathbf{b}}{\|\mathbf{b}\|} = \frac{1}{\sqrt{13}} \langle 2, 0, 3 \rangle = \left\langle \frac{2}{\sqrt{13}}, 0, \frac{3}{\sqrt{13}} \right\rangle$$

**Proof of Fact:** It's a one-liner! Just calculate the length of:

$$\left\|\frac{\mathbf{a}}{\|\mathbf{a}\|}\right\| = \left\|\frac{1}{\|\mathbf{a}\|}\mathbf{a}\right\| = \frac{1}{\|\mathbf{a}\|}\|\mathbf{a}\| = 1$$

#### **Definition:**

The standard unit vectors (in 2 dimensions) are

$$\mathbf{i} = \langle 1, 0 \rangle$$
 and  $\mathbf{j} = \langle 0, 1 \rangle$ 

And in 3 dimensions they are

$$\mathbf{i} = \langle 1, 0, 0 \rangle, \mathbf{j} = \langle 0, 1, 0 \rangle, \mathbf{k} = \langle 0, 0, 1 \rangle$$





## 5. Crazy Physics Problem

Finally, since vectors arise in physics and engineering, let's solve an application problem with them.

**Warning:** This problem is a little bit involved and likely optional for the quizzes and exams (unless mentioned otherwise)

# Example 16:

A 10-lb weight hangs from two wires as shown in the picture below. Find the forces  $\mathbf{a}$  and  $\mathbf{b}$ , as well as their lengths  $\|\mathbf{a}\|$  and  $\|\mathbf{b}\|$ .



# **STEP 1:** Find **a**

Let's focus on the left-hand-side of the picture:



(Because of alternating angles, the angle on the bottom left of the picture is also  $50^{\circ}$ ).

Now focus on the right triangle formed by  $\mathbf{a}$  in the picture below. Let's call the sides x and y, and the hypotenuse is by definition  $\|\mathbf{a}\|$  (the length of the vector  $\mathbf{a}$ )



By SOHCAHTOA, we have:

$$\cos(50) = \frac{x}{\|\mathbf{a}\|} \Rightarrow x = \|\mathbf{a}\|\cos(50)$$
$$\sin(50) = \frac{y}{\|\mathbf{a}\|} \Rightarrow y = \|\mathbf{a}\|\sin(50)$$

And therefore, we get

$$\mathbf{a} = \langle -x, y \rangle = \langle - \|\mathbf{a}\|\cos(50), \|\mathbf{a}\|\sin(50) \rangle$$

(We put a minus sign because **a** goes to the left, not to the right)

STEP 2: Find b

Similarly, we get

$$\mathbf{b} = \langle \|\mathbf{b}\|\cos(30), \|\mathbf{b}\|\sin(30) \rangle$$

(Here we have a plus sign because **b** goes to the right)

So all that is left to find is  $\|\mathbf{a}\|$  and  $\|\mathbf{b}\|$ . Once we found those, then we're done since the above equations give us  $\mathbf{a}$  and  $\mathbf{b}$ .

**STEP 3:** Find  $||\mathbf{a}||$  and  $||\mathbf{b}||$ .

(Notice so far we haven't used the weight at all)

Let  $\mathbf{F}$  be the force that the weight exerts on the wire. Since the weight is 10lbs and is pulling down the wire, we have

$$\mathbf{F} = \langle 0, -10 \rangle$$



#### **Important Observation:**

Since the weight counterbalances forces  $\mathbf{a}$  and  $\mathbf{b}$  the two wires, we must have:

$$\mathbf{a} + \mathbf{b} = -\mathbf{F} = -\langle 0, -10 \rangle = \langle 0, 10 \rangle$$

And using our equations for **a** and **b** from **STEPS 1 and 2**, this gives:

$$\underbrace{\langle - \|\mathbf{a}\|\cos(50), \|\mathbf{a}\|\sin(50)\rangle}_{\mathbf{a}} + \underbrace{\langle \|\mathbf{b}\|\cos(30), \|\mathbf{b}\|\sin(30)\rangle}_{\mathbf{b}} = \langle 0, 10\rangle$$

Comparing components, this tells us we need to solve the system:

$$\begin{cases} -\|\mathbf{a}\|\cos(50) + \|\mathbf{b}\|\cos(30) = 0\\ \|\mathbf{a}\|\sin(50) + \|\mathbf{b}\|\sin(30) = 10 \end{cases}$$

Using this and some algebra (which I'll skip here), we can solve for  $\|\mathbf{b}\|$  in terms of  $\|\mathbf{a}\|$  and ultimately find:

$$\|\mathbf{a}\| = \frac{10}{\sin(50) + \tan(30)\cos(50)} \approx 8.79 \text{ lbs}$$
$$\|\mathbf{b}\| = \frac{\|\mathbf{a}\|\cos(50)}{\cos(30)} \approx 6.53 \text{ lbs}$$

STEP 4: Using the equations in STEPS 1 and 2, we ultimately get

$$\mathbf{a} = \langle -\|\mathbf{a}\|\cos(50), \|\mathbf{a}\|\sin(50)\rangle \approx \langle -5.65, 6.73\rangle$$

$$\mathbf{b} = \langle \|\mathbf{b}\|\cos(30), \|\mathbf{b}\|\sin(30)\rangle \approx \langle 5.65, 3.27\rangle$$

## 6. The Dot Product

Let's move on to a useful way of multiplying vectors, called the dot product

## Example 17:

Let  $\mathbf{a} = \langle 1, 2 \rangle$  and  $\mathbf{b} = \langle 3, 4 \rangle$ 





 $\mathbf{a} \cdot \mathbf{b} = (1)(3) + (2)(4) = 3 + 8 = 11$ 

Note:  $\mathbf{a} \cdot \mathbf{b}$  is a **number**, not a vector. It intuitively measures how "close"  $\mathbf{a}$  and  $\mathbf{b}$  are (see below)

Example 18:

$$\langle 2, -3 \rangle \cdot \langle 4, 8 \rangle = (2)(4) + (-3)(8) = 8 - 24 = -16$$

(The dot product can be negative)

Example 19:

$$\langle 1, 2, 3 \rangle \cdot \langle 4, 5, 6 \rangle = (1)(4) + (2)(5) + (3)(6) = 4 + 10 + 18 = 32$$

Example 20:

Calculate  $\mathbf{a} \cdot \mathbf{a}$  and  $||\mathbf{a}||$ , where  $\mathbf{a} = \langle 1, 2, 3 \rangle$ 

$$\mathbf{a} \cdot \mathbf{a} = \langle 1, 2, 3 \rangle \cdot \langle 1, 2, 3 \rangle = 1^2 + 2^2 + 3^2 = 14$$

$$\|\mathbf{a}\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}$$

Notice those two are related! In fact:

Fact: 
$$\mathbf{a} \cdot \mathbf{a} = \|\mathbf{a}\|^2$$

(We'll use this fact at the end)

#### 7. Applications

There are many ways in which the dot product is useful:

(1) **Perpendicular:** First of all, it gives us a 1 second way of checking if two vectors are perpendicular.

Example 21:

Calculate  $\mathbf{a} \cdot \mathbf{b}$ , where  $\mathbf{a} = \langle 1, 1 \rangle$  and  $\mathbf{b} = \langle 1, -1 \rangle$ 

$$\langle 1,1 \rangle \cdot \langle 1,-1 \rangle = (1)(1) + (1)(-1) = 0$$

But also notice that **a** and **b** are perpendicular!



This is always true:

Fact:

**a** and **b** are perpendicular  $\Leftrightarrow$  **a**  $\cdot$  **b** = 0

#### Example 22:

Are the following two vectors perpendicular?

$$\mathbf{a} = \langle 1, 2, 7 \rangle, \mathbf{b} = \langle 3, 2, -1 \rangle$$

$$\langle 1, 2, 7 \rangle \cdot \langle 3, 2, -1 \rangle = (1)(3) + (2)(2) + (7)(-1) = 3 + 4 - 7 = 0 \checkmark$$

Hence they are perpendicular.

## Example 23:

For which t are the following vectors perpendicular

$$\mathbf{a} = \left\langle t, 5, -1 \right\rangle, \mathbf{b} = \left\langle t, t, -6 \right\rangle$$

$$\mathbf{a} \cdot \mathbf{b} = \langle t, 5, -1 \rangle \cdot \langle t, t, -6 \rangle$$
  
=(t)(t) + (5)(t) + (-1)(-6)  
=t<sup>2</sup> + 5t + 6  
=(t+2)(t+3)  
=0

Which is true if and only if t = -2 or t = -3.

(2) Geometric Interpretation: As mentioned above, the dot product measures how "close" two vectors are in terms of directions. In fact, consider the following 3 scenarios:



In the first scenario,  ${\bf a}$  and  ${\bf b}$  are close to each other, so their dot product is big

In the second scenario,  ${\bf a}$  and  ${\bf b}$  are perpendicular, so their dot product is 0

Finally, in the last scenario, **a** and **b** point away from each other so their dot product is large and negative (think -10000)

(the length of **a** and **b** also play a role, as in the formula below)

(3) Angles: In fact, one can even use the dot product to find the angle between two vectors.

#### Example 24:

Find the angle between  $\mathbf{a} = \langle 1, 2, 3 \rangle$  and  $\mathbf{b} = \langle 0, 1, -2 \rangle$ 



Angle Formula:

 $\mathbf{a} \cdot \mathbf{b} = \|\mathbf{a}\| \, \|\mathbf{b}\| \cos(\theta)$ 

Here:

$$\mathbf{a} \cdot \mathbf{b} = (1)(0) + (2)(1) + (3)(-2) = 2 - 6 = -4$$
$$\|\mathbf{a}\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}$$
$$\|\mathbf{b}\| = \sqrt{0^2 + 1^2 + (-2)^2} = \sqrt{5}$$

Therefore the angle formula gives:

$$-4 = \sqrt{14}\sqrt{5}\cos(\theta)$$
$$-4 = \sqrt{70}\cos(\theta)$$
$$\cos(\theta) = \frac{-4}{\sqrt{70}}$$
$$\theta = \cos^{-1}\left(\frac{-4}{\sqrt{70}}\right)$$
$$\theta \approx 119^{\circ}$$

(4) Physical Interpretation: If **F** is a Force and **D** is a displacement vector, then  $\mathbf{F} \cdot \mathbf{D}$  is the work done of **F** on **D**.



# Example 25:

Find the work done of a force **F** of 70 N on a displacement **D** of 100 m, given that the angle is  $35^{\circ}$ 



By the definition of work and the angle formula, we have

$$W = \mathbf{F} \cdot \mathbf{D}$$
  
=  $\|\mathbf{F}\| \|\mathbf{D}\| \cos(\theta)$   
= 70 × 100 × cos(35°)  
≈ 5734 N · m

(And N  $\cdot$  m is sometimes called Joules, J)

# Example 26:

Find the work done when a force  $\mathbf{F} = \langle 2, 0, 3 \rangle$  moves an object from A = (1, 2, 4) to B = (3, 5, 0)

The displacement is  $\mathbf{D} = \overrightarrow{AB} = \langle 3 - 1, 5 - 2, 0 - 4 \rangle = \langle 2, 3, -4 \rangle.$ 

Therefore, by the definition of work, we have

$$W = \mathbf{F} \cdot \mathbf{D} = \langle 2, 0, 3 \rangle \cdot \langle 2, 3, -4 \rangle = 4 + 0 - 12 = -8$$

#### 8. VECTOR PROJECTION

Here is the most important application of dot products: It allows us to project (or squish) a vector on another one

## Motivation:

Let  $\mathbf{b} = \langle 3, 4 \rangle$  and  $\mathbf{a} = \langle 1, 3 \rangle$  be two vectors

Consider the line L that goes through (0,0) and with slope  $\mathbf{a} = \langle 1,3 \rangle$ :



Now look at **b** (which is not L).



Notice: There are many ways of projecting (squishing) **b** on the line L, but only one that seems optimal, which is called  $\hat{\mathbf{b}}$ 



## **Definition:**

 $\widehat{\mathbf{b}}$  (or  $\operatorname{proj}_{\mathbf{a}}\mathbf{b})$  is the vector projection of  $\mathbf{b}$  on  $\mathbf{a}$ 

Note: This is sometimes called the *orthogonal* projection. Why orthogonal? Because it's precisely the vector on L such that  $\mathbf{b} - \hat{\mathbf{b}}$  and  $\mathbf{a}$  are *orthogonal*.



## How to calculate $\hat{\mathbf{b}}$ ?

First of all,  $\hat{\mathbf{b}}$  is parallel to  $\mathbf{a}$ , and so

$$\widehat{\mathbf{b}} = (\text{JUNK}) \mathbf{a}$$

This is important!  $\hat{\mathbf{b}}$  is a multiple of  $\mathbf{a}$ , **NOT** a multiple of  $\mathbf{b}$ .

Here is the formula for  $\hat{\mathbf{b}}$ . We will derive it later.

Vector Projection Formula:

$$\operatorname{proj}_{\mathbf{a}} \mathbf{b} = \widehat{\mathbf{b}} = \left(\frac{\mathbf{b} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}}\right) \mathbf{a}$$

How to remember this?

(1)  $\widehat{\mathbf{b}}$  is a multiple of  $\mathbf{a}$ , so  $\widehat{\mathbf{b}} = (\text{JUNK}) \mathbf{a}$ 

(2) Hugging Analogy: **b** hugs **a** to get  $\mathbf{b} \cdot \mathbf{a}$ , and then **a** is so happy that it hugs itself to get  $\mathbf{a} \cdot \mathbf{a}$ 

# Example 27:

Calculate  $\operatorname{proj}_{\mathbf{a}} \mathbf{b} = \widehat{\mathbf{b}}$ , where  $\mathbf{a} = \langle 1, 3 \rangle$  and  $\mathbf{b} = \langle 3, 4 \rangle$ 

You're projecting/squishing  $\mathbf{b}$  on  $\mathbf{a}$  and so

$$\widehat{\mathbf{b}} = \left(\frac{\mathbf{b} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}}\right) \mathbf{a}$$
$$= \left(\frac{\langle 3, 4 \rangle \cdot \langle 1, 3 \rangle}{\langle 1, 3 \rangle \cdot \langle 1, 3 \rangle}\right) \langle 1, 3 \rangle$$
$$= \frac{15}{10} \langle 1, 3 \rangle$$
$$= \frac{3}{2} \langle 1, 3 \rangle$$
$$= \left\langle \frac{3}{2}, \frac{9}{2} \right\rangle$$

## Example 28:

Calculate  $\operatorname{proj}_{\mathbf{a}} \mathbf{b}$ , where  $\mathbf{a} = \langle 3, 6, -2 \rangle$  and  $\mathbf{b} = \langle 1, 2, 3 \rangle$ 

$$\operatorname{proj}_{\mathbf{a}} \mathbf{b} = \widehat{\mathbf{b}} = \left(\frac{\mathbf{b} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}}\right) \mathbf{a}$$
$$= \left(\frac{\langle 1, 2, 3 \rangle \cdot \langle 3, 6, -2 \rangle}{\langle 3, 6, -2 \rangle}\right) \langle 3, 6, -2 \rangle$$
$$= \frac{9}{49} \langle 3, 6, -2 \rangle$$
$$= \left\langle\frac{27}{49}, \frac{54}{49}, \frac{-18}{49}\right\rangle$$

Why this formula works: It's not too bad if you remember the following picture:



**STEP 1:** First of all, remember that  $\hat{\mathbf{b}}$  is a multiple of  $\mathbf{a}$ , so for some constant c, we have

 $\widehat{\mathbf{b}} = c \, \mathbf{a}$ 

**STEP 2:** Now remember that  $\mathbf{b} - \hat{\mathbf{b}}$  and  $\mathbf{a}$  are perpendicular, so

$$\begin{pmatrix} \mathbf{b} - \widehat{\mathbf{b}} \end{pmatrix} \cdot \mathbf{a} = 0 (\mathbf{b} - c \mathbf{a}) \cdot \mathbf{a} = 0 \mathbf{b} \cdot \mathbf{a} - c(\mathbf{a} \cdot \mathbf{a}) = 0 c(\mathbf{a} \cdot \mathbf{a}) = \mathbf{b} \cdot \mathbf{a} c = \frac{\mathbf{b} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}}$$

Hence

$$\widehat{\mathbf{b}} = c \, \mathbf{a} = \left(\frac{\mathbf{b} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}}\right) \mathbf{a}$$

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#### 9. Scalar Projection

Related to vector projection, there is the concept of scalar projection, which we'll examine now. More precisely, let's look back at our picture with  $\hat{\mathbf{b}}$ :



**Intuitively:** the scalar projection  $\operatorname{comp}_{\mathbf{a}} \mathbf{b}$  is defined to be the (green) leg of the triangle with hypotenuse  $\|\mathbf{b}\|$  and angle  $\theta$  above.

Derivation: By SOHCAHTOA, we have

$$\cos(\theta) = \frac{\operatorname{comp}_{\mathbf{a}} \mathbf{b}}{\|\mathbf{b}\|} \Rightarrow \operatorname{comp}_{\mathbf{a}} \mathbf{b} = \|\mathbf{b}\| \cos(\theta)$$

The only issue is that this depends on the unknown angle  $\theta$ , but using the following trick we can get rid of it:

$$\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \|\mathbf{b}\| \cos(\theta)$$
$$= \|\mathbf{b}\| \cos(\theta) \frac{\|\mathbf{a}\|}{\|\mathbf{a}\|}$$
$$= \frac{\|\mathbf{a}\| \|\mathbf{b}\| \cos(\theta)}{\|\mathbf{a}\|}$$
$$= \frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\|}$$
(Angle Formula)

Therefore, we obtain:

Scalar Projection Formula:

$$\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\|}$$

Example 29:

Calculate  $\operatorname{comp}_{\mathbf{a}} \mathbf{b}$ , where  $\mathbf{a} = \langle 1, 3 \rangle$  and  $\mathbf{b} = \langle 3, 4 \rangle$ 

$$\frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\|} = \frac{\langle 1, 3 \rangle \cdot \langle 3, 4 \rangle}{\|\langle 1, 3 \rangle\|} = \frac{(1)(3) + (3)(4)}{\sqrt{1^2 + 3^2}} = \frac{15}{\sqrt{10}} = \frac{15\sqrt{10}}{10} = \frac{3\sqrt{10}}{2}$$

# Example 30:

Calculate  $\operatorname{comp}_{\mathbf{a}} \mathbf{b}$ , where  $\mathbf{a} = \langle 1, -4, 2 \rangle$  and  $\mathbf{b} = \langle 3, 8, 4 \rangle$ 

$$\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\|} = \frac{3 - 32 + 8}{\sqrt{1 + 16 + 4}} = \frac{-21}{\sqrt{21}} = -\sqrt{21}$$

#### 10. Application of Projections

Why care about projections? Here are some nice applications

**Example 31:** Let  $\mathbf{b} = \langle 3, 4 \rangle$  and  $\mathbf{a} = \langle 1, 3 \rangle$ 

Previously we found that:

$$\widehat{\mathbf{b}} = \operatorname{proj}_{\mathbf{a}} \mathbf{b} = \left\langle \frac{3}{2}, \frac{9}{2} \right\rangle$$
 and  $\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \frac{3\sqrt{10}}{2}$ 

**Application 1:** Projections are useful to find a vector that's perpendicular to a given one.

(a) Find a vector that's perpendicular to  $\mathbf{a} = \langle 1, 3 \rangle$ 



According to the picture above, the answer is *precisely*  $\mathbf{b} - \hat{\mathbf{b}}$ 

Answer: 
$$\mathbf{b} - \widehat{\mathbf{b}} = \langle 3, 4 \rangle - \left\langle \frac{3}{2}, \frac{9}{2} \right\rangle = \left\langle \frac{3}{2}, -\frac{1}{2} \right\rangle$$

**Note:** Of course here you could directly just guess  $\langle -3, 1 \rangle$ , but the point is that this technique works in any dimensions.

**Application 2:** We can use projections to find the shortest distance from a point to a line.

(b) Find the (shortest) distance from the point (3, 4) to the line L containing  $\mathbf{a} = \langle 1, 3 \rangle$ 



Again according to the picture, the answer is the length of the vector found in (a), that is  $\|\mathbf{b} - \widehat{\mathbf{b}}\|$ :

Answer: 
$$\left\| \mathbf{b} - \widehat{\mathbf{b}} \right\| = \left\| \left\langle \frac{3}{2}, -\frac{1}{2} \right\rangle \right\| = \frac{\sqrt{10}}{2}$$

**Application 3:** Finally, projections allow us to decompose vectors in a way that is especially useful in physics.

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(c) Write  $\mathbf{b} = \langle 3, 4 \rangle$  as the sum of two vectors, one parallel to  $\mathbf{a} = \langle 1, 3 \rangle$  and one perpendicular to  $\mathbf{a}$ 



Trick: 
$$\mathbf{b} = \widehat{\mathbf{b}} + (\mathbf{b} - \widehat{\mathbf{b}}) = \underbrace{\left\langle \frac{3}{2}, \frac{9}{2} \right\rangle}_{\text{parallel to } \mathbf{a}} + \underbrace{\left\langle \frac{3}{2}, -\frac{1}{2} \right\rangle}_{\text{perpendicular to } \mathbf{a}}$$

**Physics Interpretation:** 

If  $\mathbf{b}$  is force and  $\mathbf{a}$  is displacement, then:

 $\widehat{\mathbf{b}}$  is the **tangential component** of the force  $\mathbf{b}$  (along  $\mathbf{a})$ 

 $\mathbf{b} - \widehat{\mathbf{b}}$  is the **normal component** of the force (perpendicular to  $\mathbf{a}$ ).

 $\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \frac{3\sqrt{10}}{2}$  is the (signed) length of the tangential component of the force.



So in (c), we effectively rewrote the force as the sum of a tangential and normal components.