

## LECTURE: BOUNDARY-VALUE PROBLEMS

### 1. MOTIVATION

Here is some motivation in what's to follow

#### Example 1:

Consider  $y'' - 5y' + 6y = 0$

**Aux:**  $r^2 - 5r + 6 = 0 \Rightarrow r = 2$  or  $r = 3$

In the example below, the roots 2 and 3 are called the eigenvalues:

**Eigenvalues:**  $\lambda = 2$  and  $\lambda = 3$

The general solution is

$$y = Ae^{2t} + Be^{3t}$$

**Notice:** Starting from  $e^{2t}$  and  $e^{3t}$  and using only addition and multiplication, we can get the general solution  $y = Ae^{2t} + Be^{3t}$

In the example below, the “building blocks”  $e^{2t}$  and  $e^{3t}$  are called the eigenfunctions:

**Eigenfunctions:**  $y = e^{2t}$  and  $y = e^{3t}$

We “ignore” the constants because for us, there is no difference between the building blocks  $e^{2t}$  and  $e^{3t}$  and the solution  $y = Ae^{2t} + Be^{3t}$  we

can easily go from one to the other. In Linear Algebra, this is called a “basis” of solutions.

## 2. BOUNDARY-VALUE PROBLEMS (CONTINUED)

**Video:** Boundary-Value Problems

### Example 2: (continued)

Find the values of  $\lambda$  for which the ODE has nonzero solutions

$$\begin{cases} y'' = \lambda y \\ y(0) = 0 \\ y(\pi) = 0 \end{cases}$$

**Auxiliary Equation:**  $r^2 = \lambda$

**Cases 1 + 2:**  $\lambda > 0$  and  $\lambda = 0$

No nonzero solutions

**Case 3:**  $\lambda < 0$

In this case  $\lambda = -\omega^2$  where  $\omega > 0$

**Ex:**  $\lambda = -9 = -3^2$  so  $\omega = 3$

**Aux:**  $r^2 = \lambda = -\omega^2 \Rightarrow r = \pm\omega i$

$$y(t) = A \cos(\omega t) + B \sin(\omega t)$$

$$y(0) = A \cos(0) + B \sin(0) = A = 0$$

$$y(t) = B \sin(\omega t)$$

$$\begin{aligned} y(\pi) &= 0 \\ B \sin(\omega\pi) &= 0 & B \neq 0 \text{ because otherwise } y &= 0 \sin(\omega t) = 0 \\ \sin(\omega\pi) &= 0 \\ \omega\pi &= \pi m \\ \omega &= m \end{aligned}$$

Here  $m$  can be any integer, but since  $\omega > 0$ ,  $m$  needs to be any **positive** integer,  $m = 1, 2, 3, \dots$

Then  $\lambda = -\omega^2 = -m^2 = -1, -4, -9, \dots$

Moreover, from the above, we get  $y = B \sin(\omega t) = B \sin(mt)$

### Epic Conclusion:

**Eigenvalues:**  $\lambda = -m^2$  ( $m = 1, 2, \dots$ ) =  $-1, -4, -9, \dots$

**Eigenfunctions:**

$$y = \sin(mt) \quad (m = 1, 2, \dots) = \sin(t), \sin(2t), \sin(3t), \dots$$

**Note:** Compare this from before where we had  $\lambda = 2, 3$  and  $y = e^{2t}, e^{3t}$  it's an infinite version of the previous example

**Note:** This is called eigenvalue/eigenfunction by comparison with  $A\mathbf{v} = \lambda\mathbf{v}$  from linear algebra. Here we have  $y'' = \lambda y$

## 3. DERIVATIVE EXAMPLE

**Video:** Derivative Example

**Example 3:**

Find the eigenvalues and eigenfunctions of

$$\begin{cases} y'' = \lambda y \\ y'(0) = 0 \\ y'(1) = 0 \end{cases}$$

**Auxiliary Equation:**  $r^2 = \lambda$

**Case 1:**  $\lambda > 0$

Then  $r^2 = \lambda = \omega^2 \Rightarrow r = \pm\omega$ , in which case we get

$$y(t) = Ae^{\omega t} + Be^{-\omega t}$$

$$y'(t) = A\omega e^{\omega t} - B\omega e^{-\omega t}$$

$$y'(0) = A\omega - B\omega = 0 \Rightarrow A\omega = B\omega \Rightarrow A = B$$

$$y(t) = Ae^{\omega t} + Ae^{-\omega t}$$

$$y'(1) = 0$$

$$A\omega e^{\omega} - A\omega e^{-\omega} = 0$$

$$A\omega e^{\omega} = A\omega e^{-\omega}$$

$$e^{\omega} = e^{-\omega}$$

$$\omega = -\omega$$

$$\omega = 0$$

But then  $\lambda = \omega^2 = 0^2 = 0$  which contradicts  $\lambda > 0 \Rightarrow \Leftarrow$

**Conclusion:** In this case, we have no nonzero solutions

**Case 2:**  $\lambda = 0$

**Aux:**  $r^2 = 0 \Rightarrow r = 0$  (repeated twice)

$$y(t) = A + Bt$$

$$y'(t) = B$$

$$y'(0) = 0 \Rightarrow B = 0$$

$$y(t) = A + 0t = A = A \times 1$$

But then in this case  $y'(1) = 0$  is automatically satisfied.

**Conclusion:**  $\lambda = 0$  is an eigenvalue with eigenfunction  $y(t) = 1$

**Case 3:**  $\lambda < 0$

In this case  $\lambda = -\omega^2$  where  $\omega > 0$

**Aux:**  $r^2 = \lambda = -\omega^2 \Rightarrow r = \pm\omega i$

$$y(t) = A \cos(\omega t) + B \sin(\omega t)$$

$$y'(t) = -A\omega \sin(\omega t) + B\omega \cos(\omega t)$$

$$y'(0) = -A\omega \sin(0) + B\omega \cos(0) = B\omega = 0 \Rightarrow B = 0$$

$$\begin{aligned}
 y(t) &= A \cos(\omega t) \\
 y'(1) &= 0 \\
 \Rightarrow A\omega \sin(\omega 1) &= 0 \\
 \sin(\omega) &= 0 \\
 \omega &= \pi m \quad m = 1, 2, \dots
 \end{aligned}$$

Here again  $m$  starts at 1 since we have  $\omega > 0$

In that case  $\lambda = -\omega^2 = -(\pi m)^2$  and  $y = \cos(\omega t) = \cos(\pi m t)$

**Note:** If you let  $m = 0$  then  $\lambda = -(\pi 0)^2 = 0$  and  $y = \cos(\pi 0 t) = \cos(0) = 1$ , which *includes* the previous step!

### Epic Conclusion:

**Eigenvalues:**  $\lambda = -(\pi m)^2$  ( $m = 0, 1, 2, \dots$ ) =  $0, -\pi^2, -4\pi^2, \dots$

**Eigenfunctions:**

$$y = \cos(\pi m t) \quad (m = 0, 1, 2, \dots) = 1, \cos(\pi t), \cos(2\pi t), \dots$$

## 4. "MIXED" EXAMPLE

### Example 4: (extra practice)

Find the eigenvalues and eigenfunctions of

$$\begin{cases}
 y'' = \lambda y \\
 y(0) = 0 \\
 y' \left( \frac{\pi}{2} \right) = 0
 \end{cases}$$

**Auxiliary Equation:**  $r^2 = \lambda$

**Case 1:**  $\lambda > 0$

Then  $r^2 = \lambda = \omega^2$  and so  $r = \pm\omega$

$$\begin{aligned}y(t) &= Ae^{\omega t} + Be^{-\omega t} \\y(0) &= A + B = 0 \Rightarrow B = -A \\y(t) &= Ae^{\omega t} - Ae^{-\omega t} \\y'(t) &= A\omega e^{\omega t} - A(-\omega)e^{-\omega t}\end{aligned}$$

$$\begin{aligned}y'\left(\frac{\pi}{2}\right) &= 0 \\A\omega e^{\frac{\pi\omega}{2}} + A\omega e^{-\frac{\pi\omega}{2}} &= 0 \\A\omega e^{\frac{\pi\omega}{2}} &= -A\omega e^{\frac{\pi\omega}{2}} \\e^{\frac{\pi\omega}{2}} &= \underbrace{-e^{\frac{\pi\omega}{2}}}_{<0}\end{aligned}$$

$>0$                        $<0$

Which is a contradiction  $\Rightarrow \Leftarrow$

**Conclusion:** In this case, we have no nonzero solutions

**Case 2:**  $\lambda = 0$

**Aux:**  $r^2 = 0 \Rightarrow r = 0$  (repeated twice)

$$\begin{aligned}y(t) &= A + Bt \\y(0) = 0 &\Rightarrow A = 0 \\y(t) &= Bt\end{aligned}$$

$$y'(t) = B$$

$$y' \left( \frac{\pi}{2} \right) = 0 \Rightarrow B = 0$$

But then in this case  $y = 0 \Rightarrow \Leftarrow$

**Conclusion:** In this case, we have no nonzero solutions

**Case 3:**  $\lambda < 0$

In this case  $\lambda = -\omega^2$  where  $\omega > 0$

**Aux:**  $r^2 = \lambda = -\omega^2 \Rightarrow r = \pm \omega i$

$$y(t) = A \cos(\omega t) + B \sin(\omega t)$$

$$y(0) = A = 0$$

$$y(t) = B \sin(\omega t)$$

$$y'(t) = \omega B \cos(\omega t)$$

$$y' \left( \frac{\pi}{2} \right) = 0$$

$$\omega B \cos \left( \frac{\pi \omega}{2} \right) = 0$$

$$\cos \left( \frac{\pi \omega}{2} \right) = 0$$

$$\frac{\pi \omega}{2} = \frac{\pi}{2} + \pi m$$

$$\omega = 1 + 2m \quad m = 0, 1, 2, \dots$$

$$\lambda = -\omega^2 = -(2m + 1)^2 = -1, -9, -25, \dots$$



And  $y(t) = B \sin(\omega t) = B \sin((2m + 1)t)$

### Epic Conclusion:

#### Eigenvalues:

$$\lambda = -\omega^2 = -(2m + 1)^2 \quad (m = 0, 1, 2, \dots) = -1, -9, -25, \dots$$

#### Eigenfunctions:

$$y = \sin((2m + 1)t) \quad (m = 0, 1, 2, \dots) = \sin(t), \sin(3t), \sin(5t), \dots$$

## 5. INHOMOGENEOUS EQUATIONS

What if the right-hand-side of our ODE is nonzero?

### Example 5: (Model Problem)

$$y'' - 5y' + 6y = 6e^{4t}$$

#### STEP 1: Homogeneous Solution

Solve the homogeneous equation  $y'' - 5y' + 6y = 0$

$$y_0(t) = Ae^{2t} + Be^{3t}$$

#### STEP 2: Particular Solution

Find **one** solution of the original equation  $y'' - 5y' + 6y = 6e^{4t}$

See next time, the result will be:  $y_p(t) = 3e^{4t}$

**STEP 3: Answer:****Fact:**

The general solution is  $y = y_0 + y_p$

$$y = Ae^{2t} + Be^{3t} + 3e^{4t}$$

**Why this works?**

On the one hand, can check that  $y_0 + y_p$  is a sol. of  $y'' - 5y' + 6y = 3e^{4t}$

On the other hand, given  $y$  and  $y_p$ , if you define  $y_0 = y - y_p$  then can check that  $y_0$  solves  $y'' - 5y' + 6y = 0$ , so  $y_0$  is indeed a homogeneous solution, and  $y_0 = y - y_p \Rightarrow y = y_0 + y_p$

**Take-Away:** To solve inhomogeneous equations, you first solve the homogeneous equation and then you find *one* solution of the original equation.

**How to find  $y_p$ ?** We will discuss two methods. The first one is easier to apply but only works in special cases (see next time)