

Homework 5 Solutions

1. The roots are (from the order the terms are listed):

- $r = 0$, repeated twice
- $r = -4$, repeated three times
- $r = -7$
- $r = \pm 3i$, repeated three times ($r^2 + 9 = 0 \Rightarrow r = \sqrt{-9}$)
- $r = -1 \pm 3i$, repeated twice ($r^2 + 2r + 10 = 0$, use quadratic formula)

We can use this to compose the general solution:

$$y(t) = A + Bt + Ce^{-4t} + Dte^{-4t} + Et^2e^{-4t} + Fe^{-7t}$$

$$+ G \cos(3t) + H \sin(3t) + It \cos(3t) + Jt \sin(3t) + Kt^2 \cos(3t) + Lt^2 \sin(3t)$$

$$+ Me^{-t} \cos(3t) + Ne^{-t} \sin(3t) + Oe^{-t}t \cos(3t) + Pe^{-t}t \sin(3t)$$

2. Auxiliary equation: $r^2 = \lambda$

Case 1: $\lambda > 0$

Because λ is positive,

$$r^2 = \lambda \implies \pm\sqrt{\lambda}.$$

If we let $\omega = \sqrt{\lambda}$, then

$$r = \pm\omega.$$

This gives the general solution

$$y(t) = Ae^{\omega t} + Be^{-\omega t}.$$

Using the initial condition,

$$y(3) = 0 \implies Ae^{3\omega} + Be^{-3\omega} = 0$$

$$\implies B = -Ae^{6\omega}$$

so

$$y(t) = Ae^{\omega t} - Ae^{6\omega}e^{-\omega t}$$

$$\implies y'(t) = A\omega e^{\omega t} + Ae^{6\omega}\omega e^{-\omega t}$$

Using the other initial condition,

$$y'(0) = 0 \implies A\omega e^0 + Ae^{6\omega}\omega e^0 = 0$$

$$\implies A\omega + Ae^{6\omega}\omega = 0$$

$$\implies A\omega(1 + e^{6\omega}) = 0.$$

Because $(1 + e^{6\omega})$ must be positive, this implies either that $\omega = 0$ or that $A = 0$. The former contradicts our assumption that $\lambda > 0$, because $\omega = \sqrt{\lambda} > 0$. Therefore, we must have $A = 0$, and so our solution becomes $y(t) = 0$. Thus we have no nonzero solutions in the $\lambda > 0$ case.

Case 2: $\lambda = 0$ In this case, the auxiliary equation $r^2 = 0$ has a repeated root at 0, so the general solution is

$$y(t) = A + Bt.$$

Using the initial conditions,

$$y(3) = 0 \implies 0 = A + 3B$$

$$\implies A = -3B$$

$$\implies y(t) = -3B + Bt$$

$$\implies y'(t) = B$$

$$y'(0) = 0 \implies B = 0,$$

so we have $y(t) = 0$ and thus there are no nonzero solutions in this case.

Case 3: $\lambda < 0$

Because $\lambda < 0$, $r = \pm\sqrt{\lambda}$ is imaginary, so there exists some positive real ω such that $r = \pm\omega i$. Our general solution is then

$$y(t) = A \cos(\omega t) + B \sin(\omega t).$$

Using the initial condition,

$$y(3) = 0 \implies A \cos(3\omega) + B \sin(3\omega) = 0$$

$$\implies A \cos(3\omega) = -B \sin(3\omega).$$

We also have that

$$y'(t) = -A\omega \sin(\omega t) + B\omega \cos(\omega t),$$

so using the other initial condition,

$$y'(0) = 0 \implies -A\omega \sin(0) + B\omega \cos(0) = 0$$

$$\implies B\omega = 0,$$

and because $\omega \neq 0$ this implies that $B = 0$. Substituting this into our earlier equation, we have that

$$A \cos(3\omega) = 0$$

$$\implies \cos(3\omega) = 0.$$

Cosine vanishes for arguments $n\pi/2$ where n is odd, equivalently when $n = 2m + 1$ for $m \in \{0, 1, 2, \dots\}$. Therefore,

$$\begin{aligned} 3\omega &= (2m + 1)\frac{\pi}{2} \\ \implies \omega &= (2m + 1)\frac{\pi}{6} \\ \implies \lambda = -\omega^2 &= -\left((2m + 1)\frac{\pi}{6}\right)^2. \end{aligned}$$

Finally, we have that the eigenvalues are

$$\lambda = -\left((2m + 1)\frac{\pi}{6}\right)^2$$

with corresponding eigenfunctions

$$y = \cos(\omega t) = \cos\left((2m + 1)\frac{\pi}{6}t\right),$$

for $m \in \{0, 1, 2, \dots\}$.

3. First solve the complementary solution:

$$\begin{aligned} r^2 &= 5r + 4 = 0 \\ \implies r &= 4, 1 \\ \implies y_c &= C_1e^{4t} + C_2e^t. \end{aligned}$$

For the particular solution, we guess the form:

$$y_p = A \cos(2t) + B \sin(2t).$$

Plugging this into the ODE:

$$\begin{aligned} y_p'' - 5y_p' + 4y_p &= 20 \cos(2t) + 30 \sin(2t) \\ \implies -4y_p + 10A \sin(2t) - 10B \cos(2t) + 4y_p &= 20 \cos(2t) + 30 \sin(2t). \\ \implies 10A \sin(2t) - 10B \cos(2t) &= 20 \cos(2t) + 30 \sin(2t). \end{aligned}$$

For this to match, we must have $A = 3$ and $B = -2$, so

$$y_p = 3 \cos(2t) - 2 \sin(2t).$$

Our general solution is

$$\begin{aligned} y(t) &= y_c + y_p \\ &= C_1e^{4t} + C_2e^t + 3 \cos(2t) - 2 \sin(2t). \end{aligned}$$

Using the initial condition $y(0) = 1$, we have

$$C_1 + C_2 + 3 = 1$$

$$\implies C_1 = -2 - C_2. \quad (1)$$

Using the other initial condition $y'(0) = 3$, we have

$$\begin{aligned} 4C_1e^0 + C_2e^0 - 6\sin(0) - 4\cos(0) &= 3 \\ \implies 4C_1 + C_2 - 4 &= 3, \end{aligned}$$

and substituting (1) into this, we get

$$\begin{aligned} 4(-2 - C_2) + C_2 - 4 &= 3 \\ \implies -8 - 3C_2 - 4 &= 3 \\ \implies C_2 &= -5, \end{aligned}$$

and substituting this into the earlier equation we have $C_1 = 3$. Therefore, our solution is

$$y(t) = 3e^{4t} - 5e^t + 3\cos(2t) - 2\sin(2t).$$

4. (a) For the homogeneous solutions, the auxiliary equation is

$$\begin{aligned} r^2 - 3r + 2 &= 0 \\ \implies r &= 1, 2 \end{aligned}$$

So we can't guess Ae^t , instead we guess Ate^t .

- (b) First let us check if e^{2t} coincides with the homogeneous solution:

$$\begin{aligned} r^2 - 3r + 2 &= 0 \\ \implies r &= 1, 2 \end{aligned}$$

It does coincide, so we need to multiply our guess by t :

$$y_p = (e^{2t}t)(At^2 + Bt + C)$$

- (c)

$$y_p = A\sin(2t) + B\cos(2t)$$

- (d) Check if it does or does not coincide:

$$\begin{aligned} r^2 - 2r + 5 &= 0 \\ \implies r &= 1 \pm 2i \end{aligned}$$

This does coincide, so we guess

$$y_p = Ate^t \cos(2t) + Bte^t \sin(2t)$$

- (e)

5. (a)

$$\begin{aligned}(D^2 - 4D + 4I)(y) &= e^t \\ \implies (D - 2I)(D - 2I)(y) &= E^t.\end{aligned}$$

If we let $z = (D - 2I)(y)$, then we have

$$\begin{aligned}(D - 2I)(z) &= e^t \\ \implies z' - 2z &= e^t.\end{aligned}$$

We can use integrating factors to solve this. The integrating factor is

$$e^{\int -2td} = e^{-2t},$$

so we get

$$e^{-2t}z' - e^{-2t}2z = (e^{-2t}z)' = e^{-2t}e^t = e^{-t}.$$

Integrating both sides,

$$\begin{aligned}e^{-2t}z &= -e^{-t} + C_1 \\ z &= \frac{-e^{-t}}{e^{-2t}} + \frac{C_1}{e^{-2t}} \\ &= -e^t + C_1e^{2t}.\end{aligned}$$

But $z = (D - 2I)(y) = y' - 2y$, so

$$y' - 2y = -e^t + C_1e^{2t}.$$

Using the same integrating factor e^{-2t} ,

$$e^{-2t}y' - 2e^{-2t}y = (e^{-2t}y)' = -e^{-t} + C_1,$$

and by integrating both sides we get

$$\begin{aligned}e^{-2t}y &= e^{-t} + C_1t + C_2 \\ \implies y &= e^t + C_1te^{2t} + C_2e^{2t}.\end{aligned}$$

(b)

$$\begin{aligned}(D^2 - 5D + 6I)(y) &= e^{3t} \\ \implies (D - 3)(D - 2)(y) &= e^{3t}.\end{aligned}$$

If we let $z = (D - 2)(y)$, then we have

$$\begin{aligned}(D - 3)(z) &= e^{3t} \\ \implies z' - 3z &= e^{3t}.\end{aligned}$$

We can solve this with integrating factors:

$$e^{\int -3dt} = e^{-3t}$$

$$\implies (e^{-3t}z)' = 1.$$

Integrating both sides gives us

$$e^{-2t}z = t + C_1$$

$$\implies z = e^{3t}t + C_1e^{3t}.$$

But $z = (D - 2)(y) = y' - 2y$, so we have

$$y' - 2y = e^{3t}t + C_1e^{3t}.$$

Again using integrating factors:

$$e^{\int -2dt} = e^{-2t}$$

$$\implies (e^{-2t}y)' = e^t t + C_1e^t$$

and integrating both sides:

$$e^{-2t}y = (t - 1)e^t + C_1e^t + C_2$$

$$\implies y = e^{3t}(t - 1) + C_1e^{3t} + C_2e^{2t}.$$

6. We can set up this problem as:

$$\begin{cases} 2y'' + 2y' + y = 0 \\ y(0) = 5 \\ y'(0) = 3 \end{cases}$$

The term $2y''$ is $F = ma$, the $2y'$ term is damping, and the coefficient of 1 on the y term is due to the spring constant of 1. The auxiliary equation is

$$2r^2 + 2r + 1 = 0.$$

Using the quadratic formula, we get

$$r = \frac{-2 \pm 2i}{4}$$

$$\implies r = -\frac{1}{2} \pm \frac{1}{2}i,$$

which gives us the solution:

$$y(t) = Ae^{-\frac{1}{2}t} \cos\left(\frac{1}{2}t\right) + Be^{-\frac{1}{2}t} \sin\left(\frac{1}{2}t\right).$$

Using the position initial conditions:

$$y(0) = 5$$

$$\implies A = 5.$$

To use the velocity initial condition, we must take the derivative of our solution:

$$y'(t) = -\frac{1}{2}Ae^{-\frac{1}{2}t} \sin\left(\frac{1}{2}t\right) - \frac{1}{2}Ae^{-\frac{1}{2}t} \cos\left(\frac{1}{2}t\right)$$

$$+ \frac{1}{2}Be^{-\frac{1}{2}t} \cos\left(\frac{1}{2}t\right) - \frac{1}{2}Be^{-\frac{1}{2}t} \sin\left(\frac{1}{2}t\right)$$

$$y'(0) = 0 \implies -\frac{1}{2}A + \frac{1}{2}B = 0$$

$$\implies -\frac{5}{2} + \frac{1}{2}B = 3$$

$$\implies B = 11.$$

Therefore, our solution is

$$y(t) = 5e^{-\frac{1}{2}t} \cos\left(\frac{1}{2}t\right) + 11e^{-\frac{1}{2}t} \sin\left(\frac{1}{2}t\right).$$

We see that this is an oscillating but decaying solution. The damping is an energy sink in our system, and without a force term, damping will take our system into an inertial state.